AMMONIA EMISSIONS: TESTING PERSISTENCE WITH HISTORICAL DATA FROM 1770 TO 2019 IN 37 COUNTRIES

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11	ABSTRACT
12 13 14 15 16 17 18 19 20	We examine the historical time series data of ammonia emissions from 1770 to 2019 in 37 OECD countries by looking at its statistical properties in order to determine if the series display time trends and persistence. These two properties are very common in environmental data, and our results indicate that reversion to the mean only occurs in the case of Finland, while the null hypothesis of a unit root cannot be rejected in the case of Norway or Iceland. In all the other cases, the estimated value of the differencing parameter is much higher than 1, and this is consistent for the two assumptions made regarding the error term. Thus, shocks are expected to be permanent in all cases except Finland.
21	Keywords: Ammonia; NH ₃ ; time trends; persistence; long memory
22 23 24 25 26	JEL Classification: C22; Q51; Q53

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40 1. Introduction

NH₃ (ammonia) is the most abundant alkaline gas in the atmosphere, it is a highly reactive 41 42 and soluble alkaline gas, which originates from both natural and anthropogenic sources. Ammonia comes from the decomposition and volatilization of urea. High-density, 43 intensive agricultural practices are considered "hot spots of emission." Ammonia 44 emissions related to agriculture, such as the burning of biomass or the manufacture of 45 fertilizers, are also relevant. Other sources of NH3 emissions come from catalytic 46 converters in gasoline fuelled cars, landfills, sewers, composting of organic materials, 47 combustion, industry, birds and wild animals and volatilization from soils and oceans 48 49 (Sutton et al., 2000; Wilson et al., 2004).

50 Recent studies indicate that NH₃ emissions have increased worldwide in recent decades. Ammonia has impacts both locally and internationally. In the atmosphere, 51 52 ammonia reacts with acidic pollutants such as the products of NOx and SO₂ emissions to produce a fine aerosol containing ammonia (NH4+). In this sense, although the useful life 53 54 of NH₃ is relatively short (<10-100 km), NH₄+ can be transferred over longer distances (100->1000 km) (Fowler et al., 1998; Asman et al., 1998; etc.). This is a serious problem, 55 56 since NH₃ plays a very important role in the formation of atmospheric particles, the 57 degradation of visibility and the atmospheric deposition of nitrogen in sensitive ecosystems. Excess nitrogen may cause eutrophication and acidification effects in semi-58 natural ecosystems, which in turn may lead to species composition changes and other 59 60 deleterious effects (Pitcairn et al., 1998; Krupa, 2003; Van den Berg et al., 2008; Sheppard et al., 2008; Wiedermann et al., 2009 Bobbink et al., 2010; etc.). In short, the increase in 61 NH₃ emissions has a high negative impact on public and environmental health and, 62 without a doubt, on climate change (Behera et al., 2013). 63

In this paper we examine historical time series data referring to the ammonia 64 emissions in 37 countries starting in 1770 and ending in 2019. We focus on issues such 65 as the existence of deterministic terms and persistence which are both features widely 66 observed in environmental studies (Gil-Alana et al., 2017; Zhang et al., 2020; Solarin et 67 al., 2021). Our results indicate that time trends are statistically significantly positive in 68 six countries (Turkey, Australia, Canada, New Zeeland, Norway and Iceland) 69 independently of the specification of the error term, but also in Mexico, Spain, Italy, 70 Chile, Austria and Slovenia if the errors in the differenced process are uncorrelated. On 71 the other hand, mean reversion, and thus, transitory shocks, are only observed in the case 72 73 of Iceland. The unit root hypothesis cannot be rejected for Norway and Iceland, and for 74 the remaining countries the degree of differentiation seems to be significantly higher than 1. 75

The rest of the paper is structured as follows: Section 2 presents a short review on the literature on modelling environmental data; Section 3 describes the dataset and the methodology used based on the concept of fractional integration. Section 4 is devoted to the empirical results, while Section 5 concludes the paper.

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81 2. Literature review

With the increase in population, the need to generate enough food to meet this growth has also raised. Fritz Haber achieved, at the beginning of the 20th century, the synthesis of NH₃. The process consisted, basically, of converting inert gaseous N₂ into biologically active forms that were used to fertilize fields and increase food production, which made it possible to meet the demand of considerable population increases, as reported in the works by Erisman et al. (2007), Sutton et al. (2008), Reis et al. (2009) and others. But this beneficial effect resulted in the addition of an excess of anthropogenic nitrogen (N)

compounds to the atmosphere. This substantial increase has become a major problem and 89 90 concern for human health and the environment, as stated by Krupa and Moncrief (2002), Aneja et al. (2008) and Behera et al. (2013) among many others. The most important N 91 gases that are emitted by human activities are nitrogen oxides (NOx), nitrous oxide (N₂O) 92 and NH₃. From these gases, NH₃, is emitted, as explained by Olivier et al. (1998), Sutton 93 and Fowler (2000), Wilson et al. (2004), Zhang et al. (2008) and Aneja et al. (2012), by 94 a large number of sources, such as the volatilization of animal waste and synthetic 95 fertilizers, loss of soil under native vegetation and agricultural crops, human excrement 96 and combustion of fossil fuels. 97

98 The existence of NH₃ in the gaseous phase and its interaction with other substances in the atmosphere was discovered in the last century. Being the only kind of 99 primary alkaline basic gas in the atmosphere, NH₃ plays, as Shukla and Sharma (2010), 100 101 Xue et al. (2011) and Behera et al. (2013) argue, an important role in determining the general acidity of precipitation, airborne particles (aerosols and PM) and cloud water. 102 103 Ammonia and ammonium (NHx) are also nutrients that fertilize plants, as reflected in the 104 works of Asman (1995) and Sutton and Fowler (2002). However, a considerable increase in the anthropogenic contribution of N to the environment can lead to the eutrophication 105 106 of terrestrial and aquatic ecosystems, which poses a serious threat to biodiversity (see, e.g., Aneja et al., 1986; Asman et al., 1998; Pitcairn et al., 1998; Galloway et al., 2003; 107 Krupa, 2003; Erisman et al., 2005; Sheppard et al., 2008; Van den Berg et al., 2008; 108 109 Wiedermann et al., 2009, and Bobbink et al., 2010).

More recently, studies such as Charlson et al. (1990), Bauer et al. (2007) and Myhre et al. (2009) have examined the impact of the sources, the movement and destination of atmospheric NH₃ on climate change that has been taking place worldwide. NH₃ emissions have increased worldwide in recent decades, due to atmospheric ammonia

having impacts both locally and internationally as shown in the studies by Asman et al. (1998) and Fowler et al. (1998). Specifically, the effects of sulphate (SO4²⁻) and nitrate (NO₃₋) aerosols on the dispersion of incoming solar radiation have been verified. The greater the availability of aerosol particles, the greater the cloud droplet formation. As a consequence, the total accumulated area of all the droplets is larger, the resulting cloud is more reflective and remains longer (cloud life effect).

In summary, ammonia is a nitrogen-containing compound and its emissions contribute to the formation of ammonium sulphate and ammonium nitrate aerosols, which deteriorate air quality. The increase in ammonia emissions have made it, along with sulphur dioxide, nitrogen oxides and tropospheric ozone, one of the most worrying pollutants.

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126 **3.** Data and methodology

We obtained the ammonia emissions in kilotons from Feng et al. (2020). In contrast to 127 128 other databases of ammonia emissions data, this data does not suffer from lack of 129 replicability, ambiguity in the estimation process or lack of temporal resolution (Feng et al. 2020). The data preparation involves the use of emission factors, emission inventories 130 131 and activity/driver data to calculate annual national emissions for each year and there are several stages involved in the computation stage. The first stage involves collecting and 132 processing of data into a consistent format and timescale. In the second stage, driver and 133 134 emission factor data are used to calculate default emissions data for the period, 1960-2014. Consequently, emission estimates are scaled back to 1770 to obtain final figures 135 for each nation (Feng et al. 2020). They are annual data ending at 2019. 136

137 Dealing with the methodology, we use techniques based on fractional integration,138 which are very useful for the purpose of describing issues such as persistence, and time

trends in time series data. A process {xt, t = 0, ±1, ...} is said to be fractionally integrated
or integrated of order d, and represented as I(d), if it can be expressed as:

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$$(1-B)^d x_t = u_t, \qquad t = 1, 2, ...,$$
 (1)

where B is the backshift operator (i.e., $B_k x_t = x_{t-k}$) and where ut is integrated of order 0 or I(0) that means that it is second order stationary with a spectral density function that is positive and bounded at all frequencies. Within the I(0) category we have the white noise process but also other processes allowing, for example, some type of weak (ARMA) autocorrelation.

Using a Binomial expansion on the polynomial in B in the left hand side of (1), xt
can be expressed in terms of all its past history, adopting the form of an infinite AR
process,

150
$$x_t = d x_{t-1} - \frac{d(d-1)}{2} x_{t-2} + \frac{d(d-1)(d-2)}{6} x_{t-3} - \dots + u_t$$

and thus, the differencing parameter d can be taken as a measure of the degree of persistence of the data, since the higher the value of d is, the higher the association between observations is, even if they are far apart in time. The estimation is conducted via Whittle function in the frequency domain (Dahlhaus, 1989) by implementing a very simple version of Robinson's (1994) tests, widely used in recent years in empirical applications of environmental studies (see, e.g., Nikolopoulos et al., 2019; Caporale et al., 2021, Gil-Alana and Sakiru, 2021; etc.).

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159 4. Empirical results

160 We look at the following regression model,

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$$y_t = \beta_0 + \beta_1 t + x_t, \qquad (1 - L)^d x_t = u_t, \qquad t = 1, 2, ...$$
 (2)

where y_t refers to the observed time series; β_0 and β_1 are the coefficients corresponding respectively to the intercept and a linear time trend, and x_t is supposed to be I(d) where d is another parameter that is also estimated from the data. Dealing with the error term u_t , we assume first that it is a white noise process, and later, we assume (weak) autocorrelation based on Bloomfield (1973)¹. Tables 1 and 2 refer to the case of white noise errors, while Tables 3 and 4 to the model of Bloomfield (1973) for the error term.

Table 1 shows the values of the differencing parameter, d, and their 95% 168 confidence bands under the three classical assumptions in the unit root literature of: i) no 169 deterministic terms, ii) an intercept and iii) an intercept with a linear time trend, with the 170 171 selected model for each series presented in bold in the table. The first thing we observe 172 in this table is that the time trend is required in a number of cases, in particular in 13 out of the 37 countries examined; in another group of 22 countries, the intercept is statistically 173 174 significant, while for two countries (Finland and the USA) both coefficients (intercept and time trend) are found to be statistically insignificant. The estimated coefficients are 175 176 displayed in Table 2, and the highest time trend coefficient corresponds to Mexico (3.0297), followed by Turkey (2.5666) and Australia (2.1189). Moving now to the 177 178 estimated orders of integration, we observe that the results are very heterogeneous across 179 the countries: Finland is the only country showing statistical evidence of mean reversion (d < 1); the unit root null (d = 1) cannot be rejected in the cases of Norway or Iceland; for 180 all the other countries the orders of integration are substantially higher than 1. 181

Tables 3 and 4 are similar to Tables 1 and 2 but assuming that the error term is autocorrelated. However, instead of imposing a specific ARMA model for the error term, we employ a non-parametric approximation based on Bloomfield (1973). Starting with the results displayed in Table 3, we observe that the time trend coefficient is now

¹ Bloomfield (1973) proposed a non-parametric approach to approximate ARMA processes with very few parameters.

significant in only 7 countries (of which 6, the time trend was also significant under white noise errors); for 28 countries the intercept seems to be sufficient, and for Chile and Finland, no deterministic terms are required. Focussing on the estimates of d, we observe that once more, Finland is the only country displaying mean reversion; also, apart from Norway and Iceland, the unit root null rejected cannot be rejected now in the cases of Latvia and Turkey, and the null hypothesis of I(1) is rejected in all the remaining countries in favour of d > 1.

Finally, Tables 5 and 6 display summary results in relation with the time trends 193 (Table 5) and with the orders of integration (Table 6). Starting with the time trends, we 194 195 observe that if ut is autocorrelated the coefficient for the time trend is very large in the case of the US (12.6060) followed by Turkey, Australia and Canada which also display 196 large positive values under both types of specifications for the error term. These 197 198 coefficients are all positive, which is not good for the environment. On the other hand, there are 22 countries with insignificant time trends. Looking, finally, at the orders of 199 200 integration, the results are also robust across the errors, and mean reversion only seems to happen in the case of Finland (0.59 with white noise errors and 0.61 under 201 202 autocorrelation); Norway and Iceland show evidence of I(1) behaviour under the two specifications and also Latvia and Turkey with Bloomfield disturbances. In the remaining 203 countries, the degree of differentiation is significantly higher than 1. 204

One of the justifications for the foregoing empirical findings is that the drivers of ammonia tend to be persistent. According to Narayan (2007), a series which is dependent on other series which are persistent will inherit this persistence, and transmit to several other series in a country. Nguyen et al. (2020) has shown that determinants of ammonia emissions- income per capita, energy consumption per capita and foreign direct investment are very persistent.

212 5. Concluding comments

We have investigated in this work the statistical properties of ammonia (NH₃) historical time series data in 37 countries for the time period from 1770 to 2019, annually. Using fractional integration methods our results indicate that reversion to the mean only takes place in the case of Finland, while the unit root hypothesis cannot be rejected for Norway or Iceland. In the remaining cases, the estimated values of d are much higher than 1, and this result is robust across the different specifications for the error term.

219 An implication of the empirical results of this study is that, apart from Finland, shocks to ammonia emissions in these countries will have permanent effects. Therefore, 220 221 existing measures have been effective in reducing ammonia emissions in these countries. 222 Moreover, a combination of appropriate policies and technologies should be adopted to address any upsurge in ammonia emissions. There are several policies that can be utilised 223 224 to address ammonia emissions such as the introduction of emission tax, a total ban on solid urea fertilisers, the funding and expansion of conservation areas, offering incentives 225 to assist suppliers of sustainable commodities, improving private sector participation in 226 227 the supply chains of agricultural products.

The available technologies include condensers (which are utilised to eradicate ammonia by converting the gas to a liquid), wet scrubbers (which are devices used in removing ammonia from furnace flue gas or from other gas streams), urease inhibitor (which is a chemical that assists the slowing down of the conversion of urea to ammonium) and the recycling of ammonia. Countries such as the UK are in the process of introducing large scale solid urea fertilisers (Society of Chemical Industry, 2020)

Other modelling approaches still within the context of fractional integration can be taken into account. Thus, for example, non-linearities and breaks are topics which are likely to occur when using long historical data, and many authors have found that this

279	I(d) specification is very much related to these two issues (Diebold and Inoue, 2001;
280	Granger and Hyung, 2004; Ohanissian et al., 2008; etc.). Then, alternative non-linear
281	deterministic approaches, based, for example, on Chebyshev's polynomials in time
282	(Cuestas and Gil-Alana, 2016) or on Fourier transforms (Yaya et al., 2020) can be used
283	in these or in alternative datasets.
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306	Prof. Solarin Sakiru obtained the data. He worked on the introduction and literature
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330	Data are availbale from the authors upon request.
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Country	No terms	An intercept	An intercept and a linear time trend	
AUSTRALIA	1.14 (1.07, 1.23)	1.14 (1.07, 1.23)	1.15 (1.07, 1.24)	
AUSTRIA	1.15 (1.09, 1.23)	1.23 (1.17, 1.30)	1.23 (1.18, 1.30)	
BELGIUM	1.14 (1.07, 1.22)	1.15 (1.08, 1.23)	1.15 (1.08, 1.23)	
CANADA	1.19 (1.13, 1.27)	1.18 (1.12, 1.27)	1.19 (1.13, 1.28)	
CHILE	1.18 (1.13, 1.24)	1.18 (1.13, 1.24)	1.19 (1.14, 1.25)	
COLOMBIA	1.18 (1.14, 1.24)	1.18 (1.14, 1.24)	1.19 (1.15, 1.25)	
CZECH REPUBLIC	1.30 (1.22, 1.39)	1.38 (1.30, 1.46)	1.38 (1.30, 1.46)	
DENMARK	1.36 (1.29, 1.44)	1.38 (1.31, 1.46)	1.38 (1.31, 1.45)	
ESTONIA	1.46 (1.38, 1.55)	1.49 (1.41, 1.59)	1.49 (1.41, 1.59)	
FINLAND	0.59 (0.52, 0.68)	0.59 (0.53, 0.68)	0.59 (0.52, 0.68)	
FRANCE	1.10 (1.04, 1.18)	1.25 (1.20, 1.31)	1.25 (1.20, 1.31)	
GERMANY	1.32 (1.24, 1.43)	1.40 (1.31, 1.50)	1.40 (1.31, 1.50)	
GREECE	1.17 (1.11, 1.25)	1.20 (1.15, 1.27)	1.20 (1.15, 1.27)	
HUNGARY	1.37 (1.28, 1.49)	1.40 (1.30, 1.52)	1.40 (1.30, 1.52)	
ICELAND	1.05 (0.98, 1.14)	1.05 (0.98, 1.14)	1.05 (0.98, 1.15)	
IRELAND	1.16 (1.08, 1.25)	1.33 (1.26, 1.42)	1.33 (1.26, 1.42)	
ISRAEL	1.21 (1.14, 1.31)	1.22 (1.15, 1.32)	1.23 (1.16, 1.32)	
ITALY	1.06 (0.99, 1.14)	1.10 (1.05, 1.17)	1.11 (1.05, 1.18)	
JAPAN	1.13 (1.07, 1.22)	1.22 (1.16, 1.30)	1.22 (1.16, 1.30)	
KOREA	1.24 (1.19, 1.31)	1.25 (1.19, 1.31)	1.25 (1.19, 1.31)	
LATVIA	1.48 (1.37, 1.64)	1.72 (1.55, 1.94)	1.72 (1.55, 1.94)	
LITHUANIA	1.42 (1.32, 1.55)	1.46 (1.36, 1.60)	1.46 (1.36, 1.60)	
LUXEMBOURG	1.22 (1.15, 1.31)	1.24 (1.17, 1.33)	1.24 (1.17, 1.33)	
MEXICO	1.20 (1.15, 1.25)	1.20 (1.15, 1.25)	1.21 (1.16, 1.26)	
NETHERLANDS	1.24 (1.18, 1.30)	1.24 (1.18, 1.30)	1.24 (1.18, 1.30)	
NEW ZEALAND	1.14 (1.08, 1.21)	1.14 (1.08, 1.21)	1.15 (1.09, 1.22)	
NORWAY	1.01 (0.95, 1.08)	1.01 (0.95, 1.09)	1.01 (0.95, 1.09)	
POLAND	1.33 (1.24, 1.43)	1.34 (1.25, 1.45)	1.34 (1.26, 1.45)	
PORTUGAL	1.12 (1.05, 1.21)	1.14 (1.08, 1.23)	1.15 (1.08, 1.23)	
SLOVAKIA	1.15 (1.08, 1.23)	1.15 (1.09, 1.24)	1.16 (1.09, 1.24)	
SLOVENIA	1.07 (1.02, 1.13)	1.08 (1.03, 1.14)	1.08 (1.03, 1.15)	
SPAIN	1.14 (1.08, 1.21)	1.15 (1.09, 1.22)	1.15 (1.09, 1.22)	

509 Table 1: Estimates of d: White noise errors

SWEDEN	1.32	(1.25, 1.41)	1.39	(1.32, 1.47)	1.39	(1.32, 1.47)
SWITZERLAND	1.18	(1.11, 1.26)	1.26	(1.20, 1.31)	1.26	(1.20, 1.31)
TURKEY	1.15	(1.08, 1.25)	1.16	(1.09, 1.27)	1.17	(1.09, 1.28)
UK	1.20	(1.13, 1.29)	1.23	(1.16, 1.31)	1.23	(1.17, 1.32)
USA	1.31	(1.21, 1.43)	1.31	(1.21, 1.43)	1.31	(1.22, 1.43)

511 Values in parenthesis indicate the 95% confidence interval of the non-rejection values of d using

Robinson (1994). In bold, the selected specification for the deterministic terms in each series.

Country	d	Intercept (t-value)	Time trend (t-value)
AUSTRALIA	1.15 (1.07, 1.24)	-1.3130 (-0.18)	2.1189 (2.21)
AUSTRIA	1.23 (1.18, 1.30)	9.6768 (16.84)	0.2017 (1.73)
BELGIUM	1.15 (1.08, 1.23)	12.1843 (4.68)	
CANADA	1.19 (1.13, 1.28)	0.6221 (0.12)	1.6801 (1.97)
CHILE	1.19 (1.14, 1.25)	2.3065 (1.13)	0.7652 (2.29)
COLOMBIA	1.19 (1.15, 1.25)	6.2679 (1.68)	1.5465 (2.53)
CZECH REPUBLIC	1.38 (1.30, 1.46)	21.9430 (11.23)	
DENMARK	1.38 (1.31, 1.46)	7.7977 (5.93)	
ESTONIA	1.49 (1.41, 1.59)	1.8773 (5.97)	
FINLAND	0.59 (0.52, 0.68)		
FRANCE	1.25 (1.20, 1.31)	146.7798 (28.79)	
GERMANY	1.40 (1.31, 1.50)	77.3950 (9.48)	
GREECE	1.20 (1.15, 1.27)	6.4508 (6.96)	
HUNGARY	1.40 (1.30, 1.52)	16.2086 (5.38)	
ICELAND	1.05 (0.98, 1.15)	0.1397 (1.26)	0.0192 (2.19)
IRELAND	1.33 (1.26, 1.42)	35.3033 (27.48)	
ISRAEL	1.22 (1.15, 1.32)	2.0047 (5.56)	
ITALY	1.11 (1.05, 1.18)	65.0932 (11.41)	1.0835 (1.75)
JAPAN	1.22 (1.16, 1.30)	113.0488 (15.56)	
KOREA	1.25 (1.19 1.31)	9.4460 (2.78)	
LATVIA	1.72 (1.55, 1.94)	6.1218 (2.83)	
LITHUANIA	1.46 (1.36, 1.60)	6.7481 (5.90)	
LUXEMBOURG	1.24 (1.17, 1.33)	0.5513 (7.98)	
MEXICO	1.21 (1.16, 1.26)	22.7619 (2.89)	3.0297 (2.11)
NETHERLANDS	1.24 (1.18, 1.30)	10.2021 (1.66)	
NEW ZEALAND	1.15 (1.09, 1.22)	0.9234 (0.46)	0.7229 (2.73)
NORWAY	1.01 (0.95, 1.09)	1.8700 (3.14)	0.1188 (3.10)
POLAND	1.34 (1.25, 1.45)	39.4288 (4.22)	
PORTUGAL	1.14 (1.08, 1.23)	7.4941 (6.95)	
SLOVAKIA	1.15 (1.09, 1.24)	5.4500 (3.06)	
SLOVENIA	1.08 (1.03, 1.15)	1.6327 (4.65)	0.0597 (1.84)

516 Table 2: Estimated coefficients in Table 1: White noise errors

SPAIN	1.15	(1.09, 1.22)	39.7281 (5.47)	1.7364 (1.79)
SWEDEN	1.39	(1.32, 1.47)	6.3292 (11.17)	
SWITZERLAND	1.26	(1.20, 1.31)	10.6917 (14.92)	
TURKEY	1.17	(1.09, 1.28)	52.6523 (5.85)	2.5666 (1.92)
UK	1.23	(1.16, 1.31)	26.7184 (9.02)	
USA	1.31	(1.21, 1.43)		

518 519 The values in parenthesis in column 2 are the 95% confidence intervals. In columns 3 and 4 they are t-values.

Country	No terms	An intercept	An intercept and a linear time trend	
AUSTRALIA	1.12 (1.02, 1.28)	1.12 (1.02, 1.28)	1.14 (1.03, 1.29)	
AUSTRIA	1.32 (1.17, 1.49)	1.48 (1.32, 1.69)	1.49 (1.34, 1.69)	
BELGIUM	1.22 (1.09, 1.41)	1.25 (1.12, 1.42)	1.25 (1.13, 1.42)	
CANADA	1.15 (1.08, 1.25)	1.15 (1.08, 1.25)	1.16 (1.09, 1.27)	
CHILE	1.29 (1.20, 1.45)	1.29 (1.20, 1.42)	1.30 (1.21, 1.45)	
COLOMBIA	1.27 (1.21, 1.35)	1.27 (1.21, 1.35)	1.29 (1.23, 1.37)	
CZECH REPUBLIC	1.29 (1.16, 1.47)	1.41 (1.27, 1.58)	1.41 (1.27, 1.58)	
DENMARK	1.46 (1.33, 1.60)	1.44 (1.34, 1.59)	1.44 (1.34, 1.59)	
ESTONIA	1.57 (1.37, 1.82)	1.59 (1.38, 1.81)	1.59 (1.38, 1.81)	
FINLAND	0.61 (0.50, 0.73)	0.61 (0.51, 0.73)	0.61 (0.51, 0.73)	
FRANCE	1.21 (1.09, 1.36)	1.64 (1.50, 1.78)	1.64 (1.50, 1.78)	
GERMANY	1.29 (1.14, 1.47)	1.34 (1.21, 1.55)	1.34 (1.21, 1.55)	
GREECE	1.29 (1.18, 1.33)	1.36 (1.26, 1.49)	1.36 (1.26, 1.49)	
HUNGARY	1.19 (1.04, 1.38)	1.18 (1.04, 1.36)	1.18 (1.04, 1.36)	
ICELAND	0.98 (0.90, 1.06)	0.98 (0.91, 1.07)	0.98 (0.90, 1.07)	
IRELAND	1.23 (1.11, 1.40)	1.29 (1.17, 1.44)	1.29 (1.17, 1.44)	
ISRAEL	1.22 (1.12, 1.38)	1.23 (1.12, 1.39)	1.23 (1.12, 1.39)	
ITALY	1.14 (1.03, 1.29)	1.23 (1.14, 1.36)	1.24 (1.14, 1.36)	
JAPAN	0.88 (0.82, 0.97)	1.23 (1.05, 1.73)	1.22 (1.05, 1.73)	
KOREA	1.43 (1.32, 1.58)	1.44 (1.33, 1.58)	1.44 (1.33, 1.58)	
LATVIA	1.12 (0.96, 1.31)	1.00 (0.87, 1.18)	1.00 (0.87, 1.18)	
LITHUANIA	1.16 (1.00, 1.35)	1.16 (1.01, 1.34)	1.16 (1.01, 1.34)	
LUXEMBOURG	1.28 (1.14, 1.47)	1.30 (1.17, 1.47)	1.31 (1.17, 1.47)	
MEXICO	1.38 (1.30, 1.51)	1.40 (1.31, 1.52)	1.40 (1.32, 1.52)	
NETHERLANDS	1.53 (1.40, 1.69)	1.52 (1.40, 1.69)	1.52 (1.40, 1.69)	
NEW ZEALAND	1.20 (1.13, 1.34)	1.20 (1.13, 1.34)	1.24 (1.14, 1.34)	
NORWAY	1.03 (0.96, 1.15)	1.04 (0.97, 1.17)	1.05 (0.97, 1.17)	
POLAND	1.21 (1.07, 1.39)	1.20 (1.06, 1.37)	1.20 (1.06, 1.37)	
PORTUGAL	1.13 (1.03, 1.27)	1.15 (1.05, 1.28)	1.15 (1.05, 1.28)	
SLOVAKIA	1.28 (1.14, 1.46)	1.30 (1.16, 1.48)	1.30 (1.16, 1.48)	
SLOVENIA	1.31 (1.19, 1.46)	1.35 (1.23, 1.50)	1.35 (1.23, 1.50)	

521 Table 3: Estimates of d: Autocorrelated (Bloomfield) errors

	SPAIN	1.59	(1.33, 2.00)	1.55	(1.31, 2.01)	1.55	(1.31, 2.01)
	SWEDEN	1.37	(1.24, 1.53)	1.43	(1.31, 1.60)	1.43	(1.31, 1.60)
	SWITZERLAND	1.29	(1.16, 1.47)	1.41	(1.27, 1.58)	1.41	(1.27, 1.58)
	TURKEY	1.04	(0.97, 1.13)	1.01	(0.95, 1.11)	1.02	(0.94, 1.11)
	UK	1.27	(1.13, 1.45)	1.29	(1.17, 1.44)	1.30	(1.17, 1.44)
	USA	1.19	(1.08, 1.38)	1.19	(1.07, 1.38)	1.19	(1.07, 1.37)
522 523 524	Values in parenthesis indic Robinson (1994). In bold,						
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551 Table 4: Estimated coefficients in Table 3: Autocorrelation (Bloomfield) errors

Country	d	Intercept (t-value)	Time trend (t-value)
AUSTRALIA	1.14 (1.03, 1.29)	-1.3425 (-0.18)	2.1273 (2.34)
AUSTRIA	1.48 (1.32, 1.69)	9.7866 (19.12)	
BELGIUM	1.25 (1.12, 1.42)	12.1852 (4.80)	
CANADA	1.16 (1.09, 1.27)	0.5516 (0.10)	1.7160 (2.34)
CHILE	1.29 (1.20, 1.45)		
COLOMBIA	1.27 (1.21, 1.35)	7.1340 (2.01)	
CZECH REPUBLIC	1.41 (1.27, 1.58)	21.9434 (11.35)	
DENMARK	1.44 (1.34, 1.59)	7.7987 (6.07)	
ESTONIA	1.59 (1.38, 1.81)	1.8773 (1.59)	
FINLAND	0.61 (0.50, 0.73)		
FRANCE	1.64 (1.50, 1.78)	146.8149 (35.24)	
GERMANY	1.34 (1.21, 1.55)	77.3850 (9.30)	
GREECE	1.36 (1.26, 1.49)	6.4544 (7.39)	
HUNGARY	1.18 (1.04, 1.36)	16.2063 (5.13)	
ICELAND	0.98 (0.90, 1.07)	0.1340 (1.21)	0.0195 (3.20)
IRELAND	1.29 (1.17, 1.44)	35.2988 (27.18)	
ISRAEL	1.23 (1.12, 1.39)	2.0047 (5.57)	
ITALY	1.23 (1.14, 1.36)	65.7741 (12.01)	
JAPAN	1.23 (1.05, 1.73)	113.0952 (7.00)	
KOREA	1.44 (1.33, 1.58)	9.4576 (3.02)	
LATVIA	1.00 (0.87, 1.18)	6.1337 (11.89)	
LITHUANIA	1.16 (1.01, 1.34)		
LUXEMBOURG	1.30 (1.17, 1.47)	0.5514 (8.15)	
MEXICO	1.40 (1.31, 1.52)	21.4450 (3.43)	
NETHERLANDS	1.52 (1.40, 1.69)	10.2134 (1.89)	
NEW ZEALAND	1.24 (1.14, 1.34)	0.9888 (0.51)	0.6893 (1.68)
NORWAY	1.05 (0.97, 1.17)	1.8860 (3.17)	0.1180 (2.51)
POLAND	1.20 (1.06, 1.37)	39.4106 (4.07)	
PORTUGAL	1.15 (1.05, 1.28)	7.4941 (6.95)	
SLOVAKIA	1.30 (1.16, 1.48)	5.4509 (3.20)	

SLOVENIA	1.35 (1.23,	1.50)	1.6747 (5.28)	
SPAIN	1.55 (1.31,	2.01)	40.7860 (6.64)	
SWEDEN	1.43 (1.31,	1.60)	6.3294 (11.38)	
SWITZERLAND	1.41 (1.27,	1.58)	10.6393 (15.46)	
TURKEY	1.02 (0.94,	1.11)	51.8872 (5,75))	2.5485 (4.16)
UK	1.29 (1.17,	1.44)	26.7275 (9.22)	
USA	1.19 (1.07,	1.37)	3.2966 (0.09)	12.6060 (2.11)

553 554 The values in parenthesis in column 2 are the 95% confidence intervals. In columns 3 and 4 they are tvalues.

Table 5: Summary results: Statistical significant time trend coefficients

White noise errors	Autocorrelated errors
MEXICO (3.0297)	USA (12.6060)
TURKEY (2.5666)	TURKEY (2.5485)
AUSTRALIA (2.1189)	AUSTRALIA (2.1273)
SPAIN (1.7364)	CANADA (1.7160)
CANADA (1.6801)	NEW ZEALAND (0.6893)
COLOMBIA (1.5465)	NORWAY (0.1180)
ITALY (1.0835)	ICELAND (0.0195)
CHILE (0.7652)	
NEW ZEALAND (0.7229)	
AUSTRIA (0.2017)	
NORWAY (0.1188)	
SLOVENIA (0.0597)	
ICELAND (0.0192)	

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White noise errors		Autocorrelated errors			
d < 1	d = 1	d > 1	d < 1	d = 1	d > 1
	NORWAY (1.01) ICELAND (1.05)	SLOVENIA (1.08) ITALY (1.11) PORTUGAL (1.14) NEW ZEALAND (1.15) SLOVAKIA (1,.15) SPAIN (1.15) TURKEY (1.17) CANADA (1.19) CHILE (1.19) COLOMBIA (1.19) GREECE (1.20) MEXICO (1.21) ISRAEL (1.22) JAPAN (1.22) UK (1.23) NETHERLANDS (1.24) FRANCE (1.25) KOREA (1.25) SWITZERLAND (1.26) USA (1.31) IRELAND (1.33) POLAND (1.34) CZECH REP. (1.38) DENMARK (1.38) SWEDEN (1.39) GERMANY (1.40) HUNGARY (1.40) LITUANIA (1.46) ESTONIA (1.49) LATVIA (1.72)	FINLAND (0.61)	ICELAND (0.98) LATVIA (1.00) TURKEY (1.02) NORWAY (1.05)	AUSTRALIA (1.14) PORTUGAL (1.15) LITIHUANIA (1.16) C.ANADA (1.16) HUNGARY (1.18) POLAND (1.20) ISRAEL (1.23) ITALY (1.23) JAPAN (1.23) NEW ZEALAND (1.24) BELGIUM (1.25) COLOMBIA (1.27) IRELAND (1.29) CHILE (1.29) UK (1.29) SLOVAKIA (1.30) LUXEMBOURG (1.31) GERMANY (1.34) SLOVENIA (1.35) GREECE (1.36) MEXICO (140) SWITZERLAND (1.41) CZECH REP. (1.41) SWEDEN (1.43) KOREA (1.44) AUSTRIA (1.48) NETHERLANDS (1.52) SPAIN (1.55) ESTONIA (1.59) FRANCE (1.64)

567 Table 6: Summary results: Orders of integration